# PHY 604: Computational Methods in Physics and Astrophysics II

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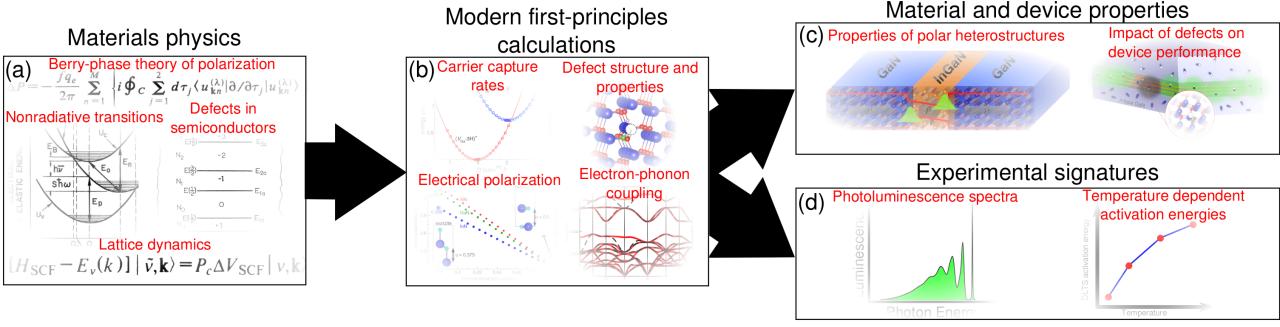
Fall 2025

### My research interests: Computational condensed matter physics





https://www.simonsfoundation.org/flatiron/



https://you.stonybrook.edu/cdreyer/

### Goals of the course:

Learn how to solve problems in physics computationally

Understand the limitations of numerical methods

 Have the ability to interpret numerical results presented in the literature

Have exposure to computational tools

 Understand basic idea behind algorithms for performing common computational tasks

# Technical points about the class: Programming Languages

- The assignments will involve writing computer programs
- You may use the programming language of your choice.\* I would prefer:
  - Fortran
  - C++
  - Matlab
  - Python (recommended)
- \* In general, and especially if your language is not on the list, you should provide some help for how to compile (if necessary) and run your code
- Examples will be given mostly in python

# Technical points about the class: Topics covered

- Basics of computation and programming constructions
- Good programming practices
- Numerical differentiation and integration
- Interpolation and root finding
- Ordinary differential equations
- Linear algebra
- Fast Fourier transforms
- Fitting
- Partial differential equations
- Monte Carlo techniques
- Genetic algorithms
- Parallel computing
- Machine learning

### Technical points about the class: Class location

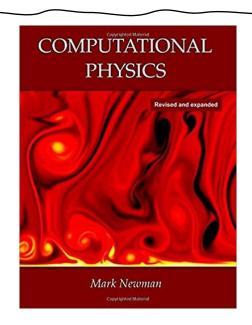
• Vote: Move the class to Physics building (likely B131)

# Technical points about the class: Assignments

- Coding homework will be assigned roughly every two weeks
  - Homeworks will be 50% of the final grade
  - Will involve code and written analysis
  - Recommendation (not required): Use Jupyter notebooks
- Office hours: By appointment
  - Please feel free to come to me for help!
- There will be a final project at the end of the semester
  - Solve a physics problem computationally
  - Write up a short report, and present to the class
  - Final project is 50% of the final grade

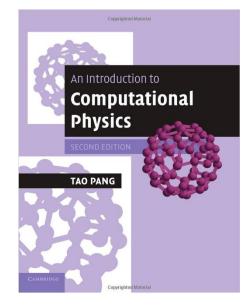
### Technical points about the class: Textbooks

- No textbook is required for this course
  - Some recommended texts for further reading:



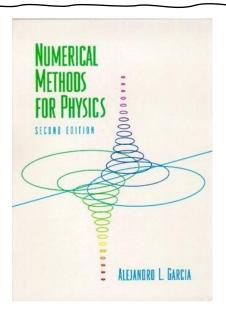
#### Computational Physics, by Mark Newman

- Generally good coverage on most of the topics we'll discuss
- Lots of physics examples
- Inexpensive
- Main recommended book



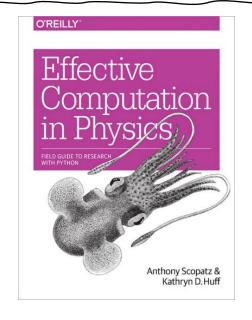
### An Introduction to Computational Physics, by Tao Pang

- Also good coverage of the topics (up to PDEs)
- Lots of physics examples
- Inexpensive



### *Numerical Methods for Physics* by Alejandro Garcia

- Broad coverage
- More PDE stuff than Pang



### Effective Computation in Physics by Scopatz & Huff

- Introduces linux/unix shell
- Covers programming practices
- Introduces parallel programming

### Why computation?

"Computational science now constitutes what many call the third pillar of the scientific enterprise, a peer alongside theory and physical experimentation."

—President's information technology advisory committee (2005)

Computation allows us to go beyond analytically solvable problems

Computers allow us to perform repetitive tasks efficiently

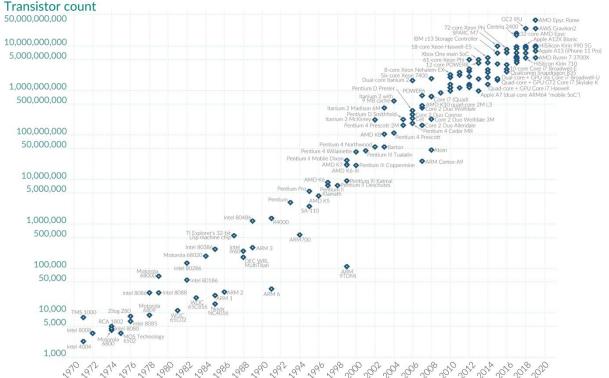
Computers allow us to generate and analyze large amounts of data

### The two roles of computational in physics research

 Calculation: Using computers to solve well-defined problems  Simulation: Use the computer to perform computational experiments

# Computational science is driven by more powerful computers

### Moore's Law: The number of transistors on microchips doubles every two years Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important for other aspects of technological progress in computing – such as processing speed or the price of computers.



Data source: Wikipedia (wikipedia.org/wiki/Transistor_count)	Year in which the microchip was f	first introduced	
OurWorldinData.org - Research and data to make progress aga	ainst the world's largest problems.	Licensed under CC-BY by the authors Hannah Ritchie and Max	Roser

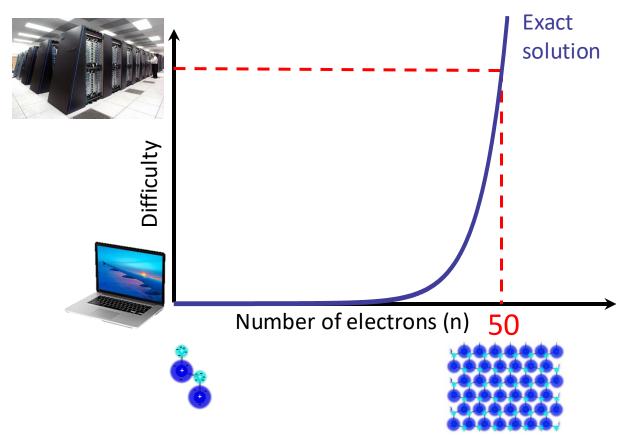
Rank	System	Cores	Rmax (PFlop/s)	Rpeak (PFlop/s)	Power (kW)
1	El Capitan - HPE Cray EX255a, AMD 4th Gen EPYC 24C 1.8GHz, AMD Instinct MI300A, Slingshot-11, TOSS, HPE DOE/NNSA/LLNL United States	11,039,616	1,742.00	2,746.38	29,581
2	Frontier - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Slingshot-11, HPE Cray OS, HPE DOE/SC/Oak Ridge National Laboratory United States	9,066,176	1,353.00	2,055.72	24,607
3	Aurora - HPE Cray EX - Intel Exascale Compute Blade, Xeon CPU Max 9470 52C 2.4GHz, Intel Data Center GPU Max, Slingshot-11, Intel DOE/SC/Argonne National Laboratory United States	9,264,128	1,012.00	1,980.01	38,698
4	JUPITER Booster - BullSequana XH3000, GH Superchip 72C 3GHz, NVIDIA GH200 Superchip, Quad-Rail NVIDIA InfiniBand NDR200, RedHat Enterprise Linux, EVIDEN EuroHPC/FZJ Germany	4,801,344	793.40	930.00	13,088
5	Eagle - Microsoft NDv5, Xeon Platinum 8480C 48C 2GHz, NVIDIA H100, NVIDIA Infiniband NDR, Microsoft Azure Microsoft Azure United States	2,073,600	561.20	846.84	

# Computational science is driven by better methods/algorithms

$$\hat{H} = -\frac{\hbar}{2m_e} \sum_{i} \nabla_i^2 - \sum_{i,I} \frac{Z_I e^2}{|\mathbf{r}_i - \mathbf{R}_I|} + \frac{1}{2} \sum_{i \neq j} \frac{e^2}{|\mathbf{r}_i - \mathbf{r}_j|} - \sum_{I} \frac{\hbar^2}{2M_I} \nabla_I^2 + \frac{1}{2} \sum_{I \neq J} \frac{Z_I Z_J}{|\mathbf{R}_I - \mathbf{R}_J|}$$

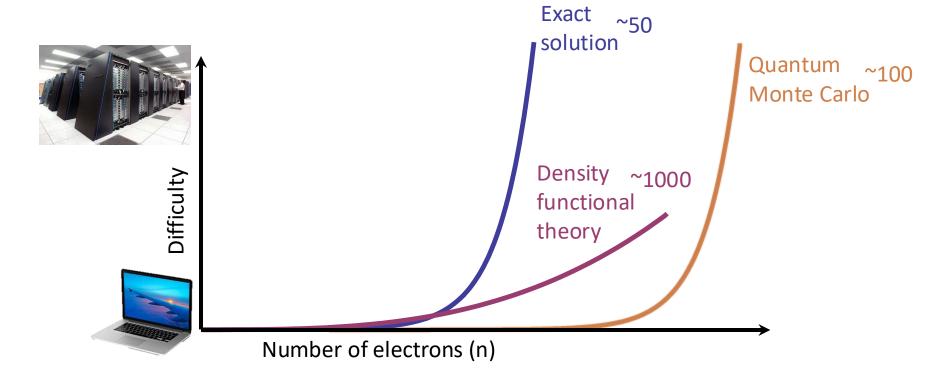
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### Goals for (the rest of) this lecture

- Representing numbers on the computer
  - Types
  - Finite precision of floating points
  - Comparing real numbers

### Information in computer programs categorized by "Type"

Fortran Equivalent

complex

C++ Type

complex (complex type

C++ standard library)

implemented as a Template class in

3 3 1 2					
short (also called short int)	Iso called short int)  integer (4)  Positive or negative number with no decimal places.		56478, 3, -278		
int	integer				
long (also called long int)	integer(8)				
float	real	Positive or negative number with	3.0, 1.67e10, -3.2234e-20		

**Description** 

Complex numbers

Example

3.0+5.6i

decimal places. double rea1(8) long double real (16)

Single or multiple letters, numbers, char character (1) a, abj3a, gh &w symbols with no special interpretation string (string type implemented character (len=\*) (as of Fortran as a container in C++ standard 2008 standard) library) True or False logical bool .True., False

### All information in a computer stored as bits

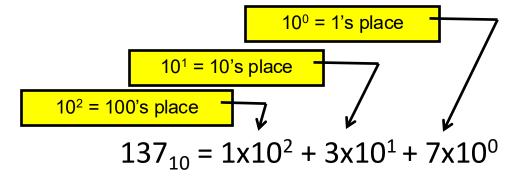
- Basic unit of information in a computer is a bit: 0 or 1
  - 8 bits = 1 byte

All types must be converted into some number of bytes

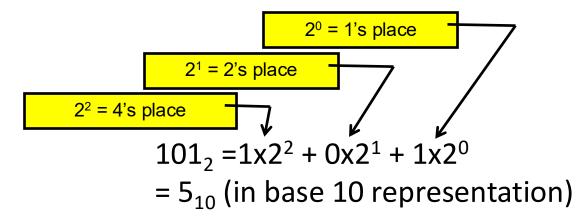
• Finite storage limits, e.g., the size or precision of a number

### Binary data representation

- "Human" representation: Base ten (decimal)
  - Each digit multiplies a power of 10



- "Computer" representation: Base two (binary)
  - Each digit multiplies a power of 2:



### The amount of memory allocated to an integer determines largest number that can be stored

- 2-byte:
  - This can store 2<sup>15</sup>-1 distinct values: -32,768 to 32,767 (signed)
  - Or it can store 2<sup>16</sup> values: 0 to 65,535 (unsigned)
- Standard in many languages is 4-bytes
  - This can store 2<sup>31</sup>-1 distinct values: -2,147,483,648 to 2,147,483,647 (signed)
    - C/C++: int (usually) or int32\_t
    - Fortran: integer or integer(4)
  - Or it can store 2<sup>32</sup> distinct values: 0 to 4,294,967,295 (unsigned)
    - C/C++: uint or uint32 t
    - Fortran (as of 95): unsigned
- For very big integers, 8-byte allows for 2<sup>64</sup>
  - Fotran: integer(8)
  - C++: long

# Overflow: Trying to put more information in a type than will fit

- What happens when you try to store an integer that too large for the memory allocated?
  - Depends on the language!

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• Fortran: Just gives you the wrong result

 Python: Allows the size of the integer to scale with the size of the number

# Another aspect of integers to keep in mind: **Integer division**

 Multiplication of integers results in an integer; addition/subtraction of integers result in an integer; division of integers does not always result in an integer!!

• What happens if we divide two integers like: 1/2?

# Another aspect of integers to keep in mind: **Integer division**

 Multiplication of integers results in an integer; addition/subtraction of integers result in an integer; division of integers does not always result in an integer!

- What happens if we divide two integers like: 1/2?
  - In some codes, 1/2 gives 0, in others it converts to real and give 0.5
  - Common source of bugs!!

# Integers versus real/floating-point: Mind the decimal place

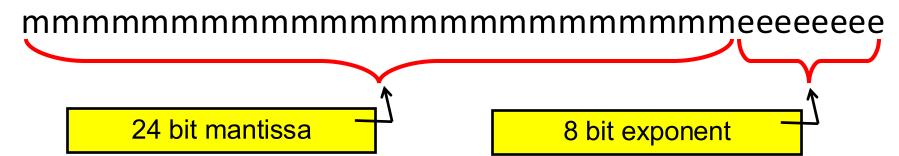
- Keep in mind that in many languages, 2 and 2.0 (or 2.) are interpreted differently
  - 2 is taken to be an integer
  - 2. or 2.0 is taken to be real
- This can be important in a variety of contexts:
  - Integers are stored exactly, floats are approximate
  - Integer and floating-point division are different
  - Exponentiating negative numbers can be problematic (-3.5)\*\*(2) is safer than (-3.5)\*\*(2.0)
  - Integers must be used for, e.g., array indices

# Real/Floating point numbers are more complicated

- Infinite real numbers on the number line need to be represented by a finite number of bits
- Finite memory results in limited size and precision of floating point numbers
  - Not all real numbers (even simple ones) can be stored in a finite number of digits in a base-2 representation
  - Example:  $1/10=0.1_{10}=0.0001100110011..._2$  does not have a finite representation in base 2 just as  $1/3=0.333333..._{10}$  has no finite representation in base 10
- This means that even simple floating point numbers are often approximated with some small error
  - This means that floating point arithmetic is not exact! (on all computers and programming languages)
- Errors can compound if not treated carefully!

### Real (a.k.a. floating point) data

• IEEE 754 mantissa-exponent form:



- Value = mantissa x 2 exponent
- Single precision:
  - Sign: 1 bit; exponent: 8 bits; significand: 24 bits (23 stored) = 32 bits
  - Range:  $2^7$ -1 in exponent (because of sign) =  $2^{127}$  multiplier ~  $10^{38}$
  - Decimal precision: ~6 significant digits
- Double precision:
  - Sign: 1 bit; exponent: 11 bits; significand: 53 bits (52 stored) = 64 bits
  - Range:  $2^{10}$ -1 in exponent =  $2^{1023}$  multiplier ~  $10^{308}$
  - Decimal precision: ~15 significant digits

### Finite precision of floating points

- This means that most real numbers do not have an exact representation on a computer.
  - Spacing between numbers varies with the size of numbers
  - Relative spacing is constant

relative roundoff error 
$$=\frac{|\text{true number} - \text{computer number}|}{|\text{true number}|} \le \epsilon$$

### Overflows/underflows with reals

- Overflows and underflows can still occur when you go outside the representable range.
  - The floating-point standard will signal these (and compilers can catch them)
- Some special numbers:
  - NaN = **0/0** or  $\sqrt{-1}$
  - Inf is for overflows, like 1/0
  - Both of these allow the program to continue, and both can be trapped (and dealt with)
- -0 is a valid number, and -0 = 0 in comparison
- Floating point is governed by an IEEE standard
  - Ensures all machines do the same thing
  - Aggressive compiler optimizations can break the standard

# A result of finite precision: Need to be careful when comparing floats/reals

- Floating point numbers involve rounding and imprecision, which propagate in different ways under different operations
- Mathematically analogous expressions may yield slightly (or significantly as we will see!) different results
- In principle, this can be accounted for since floating point operations follow specific rules
  - see reading "What Every Computer Scientist Should Know About Floating-Point Arithmetic," by David Goldberg
- In practice, it best to do an "epsilon check"

### Epsilon check for comparing floats

- Take two real numbers a and b
- We take a==b if abs(a-b) < epsilon

- Have to be very careful with this!!! We should think about:
  - The choice of epsilon based on the precision we require/expect for a and b
  - The choice of epsilon based on the magnitude of a and b
  - What will happen in special cases (0, NaN, inf)
  - •

### OTB: Round-off error example

- Imagine that we can only keep track of 4 significant digits
- Compute  $\sqrt{x+1} \sqrt{x}$
- Take x = 1984. Keeping only 4 digits each step of the way:

$$\sqrt{x+1} - \sqrt{x} = 44.55 - 44.54 = 0.01$$

- We've lost a lot of precision
- Instead, consider:

$$\sqrt{x+1} - \sqrt{x} = (\sqrt{x+1} - \sqrt{x}) \left( \frac{\sqrt{x+1} + \sqrt{x}}{\sqrt{x+1} + \sqrt{x}} \right) = \frac{1}{\sqrt{x+1} + \sqrt{x}}$$

Then

$$\sqrt{1985} - \sqrt{1984} = \frac{1}{\sqrt{1985} + \sqrt{1984}} = \frac{1}{44.55 + 44.54} = 0.01122$$

### Truncation errors are different from roundoff

 Translating continuous mathematical expressions into discrete forms introduces truncation error

• For example: 
$$e^x \simeq S(x) = 1 + \frac{x}{1!} + \frac{x^2}{2!} + ... + \frac{x^n}{n!}$$

• Error: 
$$\frac{|x|^{n+1}}{(n+1)!} \max\{1, e^x\}$$

• Or 
$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
 vs.  $D_h(x) = \frac{f(x+h) - f(x)}{h}$ 

### Floating point arithmetic not associative

Adding lots of numbers together can compound round-off error

One solution: sort and add starting with the smallest numbers

- Kahan summation (see reading list)
  - Algorithm for adding sequence of numbers while minimizing roundoff accumulation
  - Keeps a separate variable that accumulates small errors
  - Requires that the compiler obey parenthesis

### Floating point arithmetic not associative:

$$(1.0 - 1.0) + 1.0^{-9} \stackrel{?}{=} 1.0 + (-1.0 + 1.0^{-9})$$

```
! Purpose: Test the precision of reals
! Author: Cyrus Dreyer
! Date: 2/4/2019
program test prec reals
 implicit none     ! Turn off implicit typing
 ! Variable dictionary
 real :: factor1 ! Variable for factor 1
 real :: factor2 ! Variable for factor 2
 real :: prec test lhs ! Variable for result
 real :: prec test rhs ! Variable for result
 factor1 = 1.0     ! Assign a value to factor1
 factor2 = 1.0d-9
! Assign a value to factor2
 prec test lhs = (factor1-factor1) + factor2 ! LHS of inequality on slide
 prec test rhs = factor1 + (-factor1 + factor2) ! RHS of inequality on slide
 ! Output
 write(*,'(a20,e20.12e2,a20,e20.12e2)') "Prec test lhs:",prec test lhs, &
      "Prec test rhs:", prec test rhs
 stop 0 ! Stop execution of the program
end program test prec reals
```

### Further reading

#### Readings:

- What every computer scientist should know about floating-point arithmetic
- Wikipedia page on the Floating Point
- Wikipedia page on the Kahan Summation Algorithm