

PHY604 Lecture 18

October 28, 2025

Today's lecture: PDEs

- Stability analysis of PDEs
- Implicit schemes

Stability analysis of PDEs

- Empirically, we found that stability was a significant problem for PDEs
- In most cases, the stability was conditional on the timestep
 - Often related to the spatial discretization
- It is useful to be able to test for stability before running the calculation

Stability analysis of the advection equation

- Consider the advection equation discussed previously:

$$\frac{\partial a}{\partial t} = -c \frac{\partial a}{\partial x}$$

- FTCS was always unstable
 - Other methods were unstable for timesteps that were too large compared to the spatial discretization h
-
- Let's consider a trial solution of the form:

$$a(x, t) = A(t)e^{ikx}$$

 Complex
amplitude

von Neumann stability analysis

- In discretized form: $a_j^n = A^n e^{ikjh}$

- Advancing the solution by one step:

$$a_j^{n+1} = A^{n+1} e^{ikjh} = \xi A^n e^{ikjh}$$

- ξ is the **amplification factor**
- **von Neumann stability analysis**: Insert this trial solution into the numerical scheme and solve for amplification factor given h and τ
 - Unstable if $|\xi| > 1$

Stability of FTCS for advection equation

- FTCS scheme: $a_i^{n+1} = a_i^n - \frac{c\tau}{2h}(a_{i+1}^n - a_{i-1}^n)$
- Insert trial solutions: $a_j^n = A^n e^{ikjh}$ $a_j^{n+1} = \xi A^n e^{ikjh}$

$$\begin{aligned}\xi A^n e^{ikjh} &= A^n e^{ikjh} - \frac{c\tau}{2h} \left[A^n e^{ik(j+1)h} - A^n e^{ik(j-1)h} \right] \\ &= A^n e^{ikjh} \left[1 - \frac{c\tau}{2h} (e^{ikh} - e^{-ikh}) \right] \\ &= A^n e^{ikjh} \left[1 - i \frac{c\tau}{h} \sin(kh) \right]\end{aligned}$$

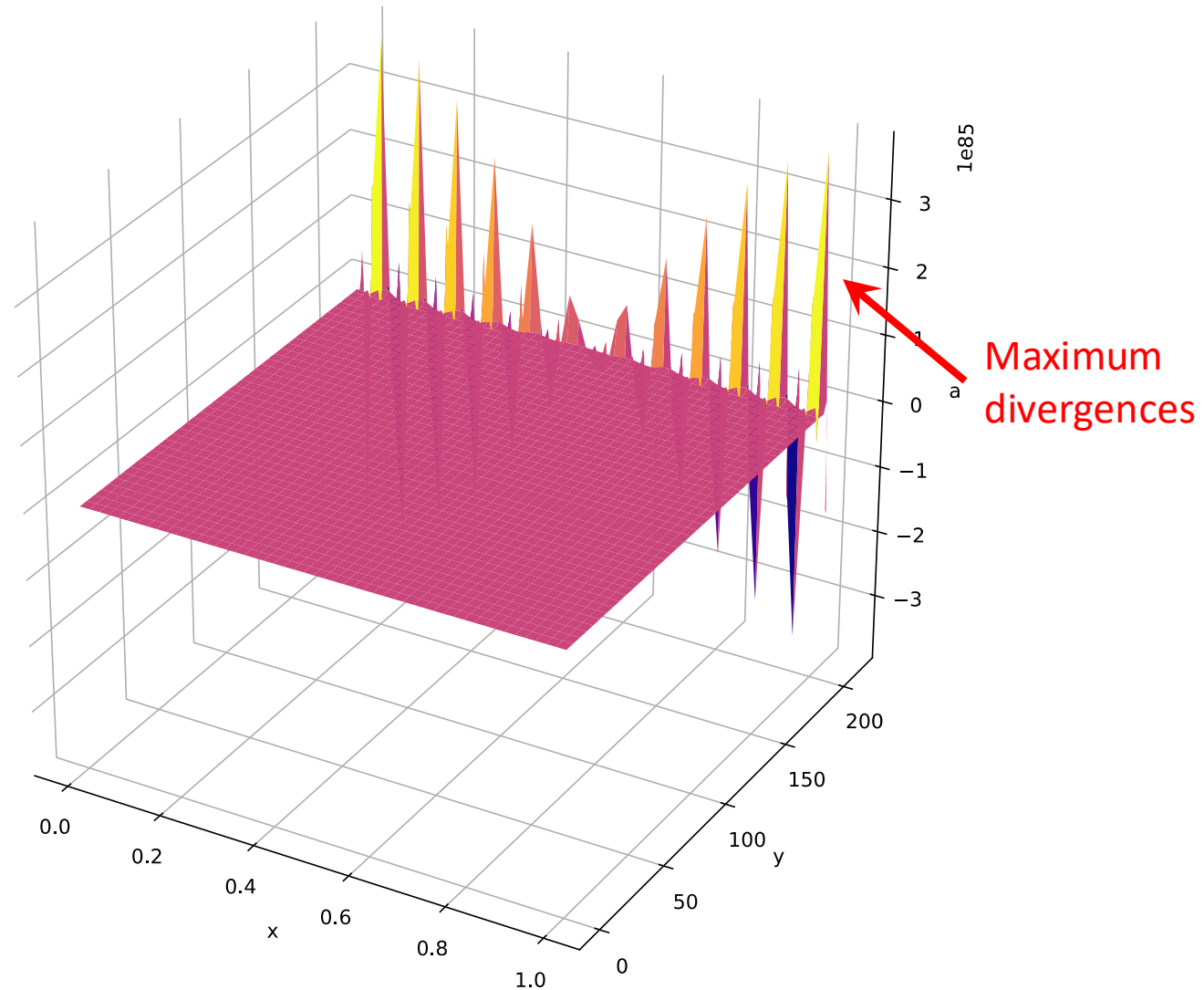
- Therefore:

$$|\xi| = \left| 1 - i \frac{c\tau}{h} \sin(kh) \right|$$

FTCS is not stable for advection equation

- We have that: $|\xi| = \left| 1 - i \frac{c\tau}{h} \sin(kh) \right| = \sqrt{1 + \left(\frac{c\tau}{h} \right)^2 \sin^2(kh)}$
- So, the solution in general grows with each timestep, and therefore unstable
- Degree to which it is unstable depends on the “mode” k
- Fastest growing mode is when: $\sin^2(k_{\max}h) = 1$
- Or: $k_{\max} = \frac{\pi}{2h}$
- Since $k=2\pi/\lambda$: $\lambda_{\max} = 4h$

Divergent modes for FTCS on advection equation



von Neumann stability of the Lax scheme

- Apply the same analysis to the Lax method:

$$a_i^{n+1} = \frac{1}{2}(a_{i+1}^n + a_{i-1}^n) - \frac{c\tau}{2h}(a_{i+1}^n - a_{i-1}^n)$$

- Plugging in our trial solution:

$$\begin{aligned}\xi A^n e^{ikjh} &= \frac{1}{2} \left[A^n e^{ik(j+1)h} + A^n e^{ik(j-1)h} \right] - \frac{c\tau}{2h} \left[A^n e^{ik(j+1)h} - A^n e^{ik(j-1)h} \right] \\ &= A^n e^{ikjh} \left[\frac{1}{2} (e^{ikh} + e^{-ikh}) - \frac{c\tau}{2h} (e^{ikh} - e^{-ikh}) \right]\end{aligned}$$

- So:
$$\xi = \cos(kh) - i \frac{c\tau}{h} \sin(kh)$$

Stability of the Lax scheme

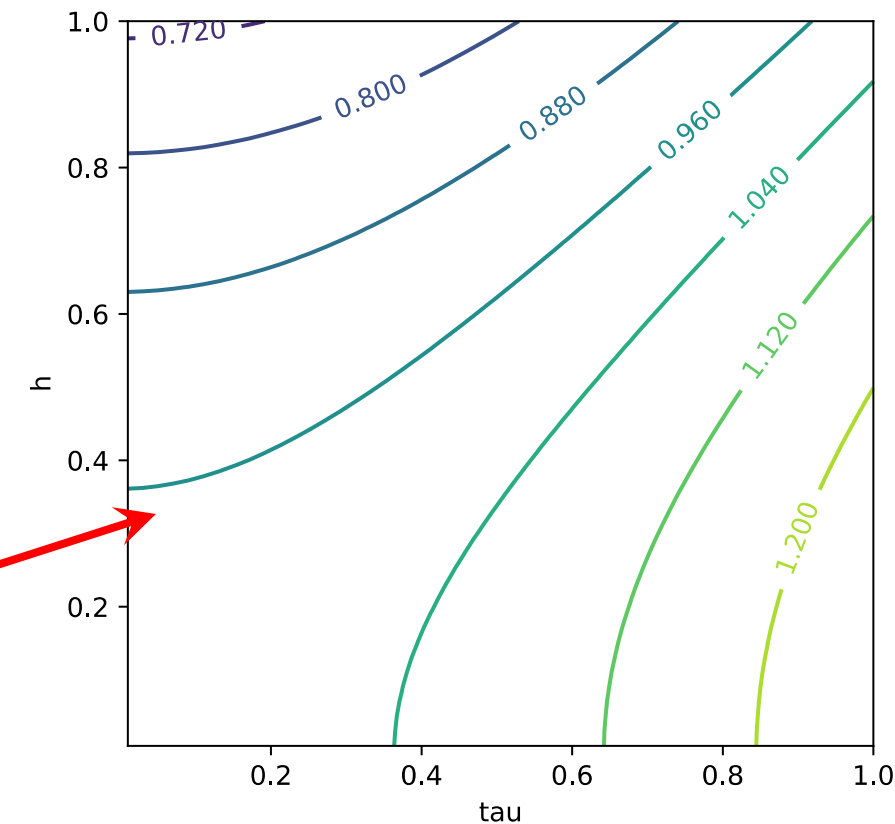
- So, we have: $|\xi| = \sqrt{\cos^2(kh) + \left(\frac{c\tau}{h}\right)^2 \sin^2(kh)}$

- Example: take $k=\pi/4$, $c=1$:

- In general: $\left|\frac{c\tau}{h}\right| \leq 1$

- Same as the Courant-Friedrichs-Lewy stability criterion

τ must be less than
or equal to h



Matrix stability analysis

- von Neumann approach is a simple and popular way to investigate the stability of solution scheme
- However, does not take into account the **influence of boundary conditions**
- Recall our discussion of relaxation methods in terms of iteratively solving linear equations
- **Matrix stability analysis**: Analyze the linear problem to see how stable the PDE solution will be

FTCS for diffusion equation

- Consider the FTCS method for the 1D diffusion equation:

$$T_j^{n+1} = T_j^n + \frac{\tau}{2t_\sigma} (T_{j+1}^n + T_{j-1}^n - 2T_j^n)$$

- Where: $t_\sigma = h^2/2\kappa$
- For Dirichlet boundary conditions we can write FTCS as:

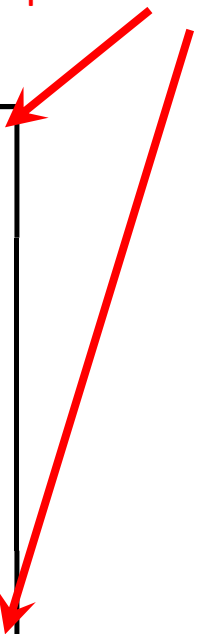
$$\begin{aligned}\mathbf{T}^{n+1} &= \mathbf{T}^n + \frac{\tau}{2t_\sigma} \mathbf{D} \mathbf{T}^n \\ &= \left(\mathbf{I} + \frac{\tau}{2t_\sigma} \mathbf{D} \right) \mathbf{T}^n \\ &= \mathbf{A} \mathbf{T}^n\end{aligned}$$

Matrix form of the diffusion equation

$$\mathbf{T}^{n+1} = \left(\mathbf{I} + \frac{\tau}{2t_\sigma} \mathbf{D} \right) \mathbf{T}^n$$

$$\mathbf{T}^n = \begin{bmatrix} T_0^n \\ T_1^n \\ T_2^n \\ T_3^n \\ \vdots \\ T_{N-1}^n \end{bmatrix}, \quad \mathbf{D} = \begin{bmatrix} 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & -2 & 1 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & \dots & 0 \\ 0 & 0 & 1 & -2 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 \end{bmatrix}$$

Zero rows so boundary
points don't change



Decomposing in eigenvectors

- To determine the stability of the problem $\mathbf{T}^{n+1} = \mathbf{A}\mathbf{T}^n$ consider the eigenvalue problem for the matrix $\mathbf{A}$:

$$\mathbf{A}\mathbf{v}_k = \lambda_k \mathbf{v}_k$$

- Assuming eigenvectors form a complete basis, initial conditions may be written as:

$$\mathbf{T}^1 = \sum_{k=0}^{N-1} c_k \mathbf{v}_k$$

- Then we can get $\mathbf{T}$ at a later time by repeatedly applying $\mathbf{A}$:

$$\mathbf{T}^{n+1} = \mathbf{A}\mathbf{T}^n = \mathbf{A}(\mathbf{A}\mathbf{T}^{n-1}) = \mathbf{A}^2(\mathbf{A}\mathbf{T}^{n-2}) = \dots = \mathbf{A}^n \mathbf{T}^1$$

- Using our eigenvector decomposition

$$\mathbf{T}^{n+1} = \sum_{k=0}^{N-1} c_k \mathbf{A}^n \mathbf{v}_k = \sum_{k=0}^{N-1} c_k (\lambda_k)^n \mathbf{v}_k$$

Stability condition on eigenvalues

$$\mathbf{T}^{n+1} = \sum_{k=0}^{N-1} c_k (\lambda_k)^n \mathbf{v}_k$$

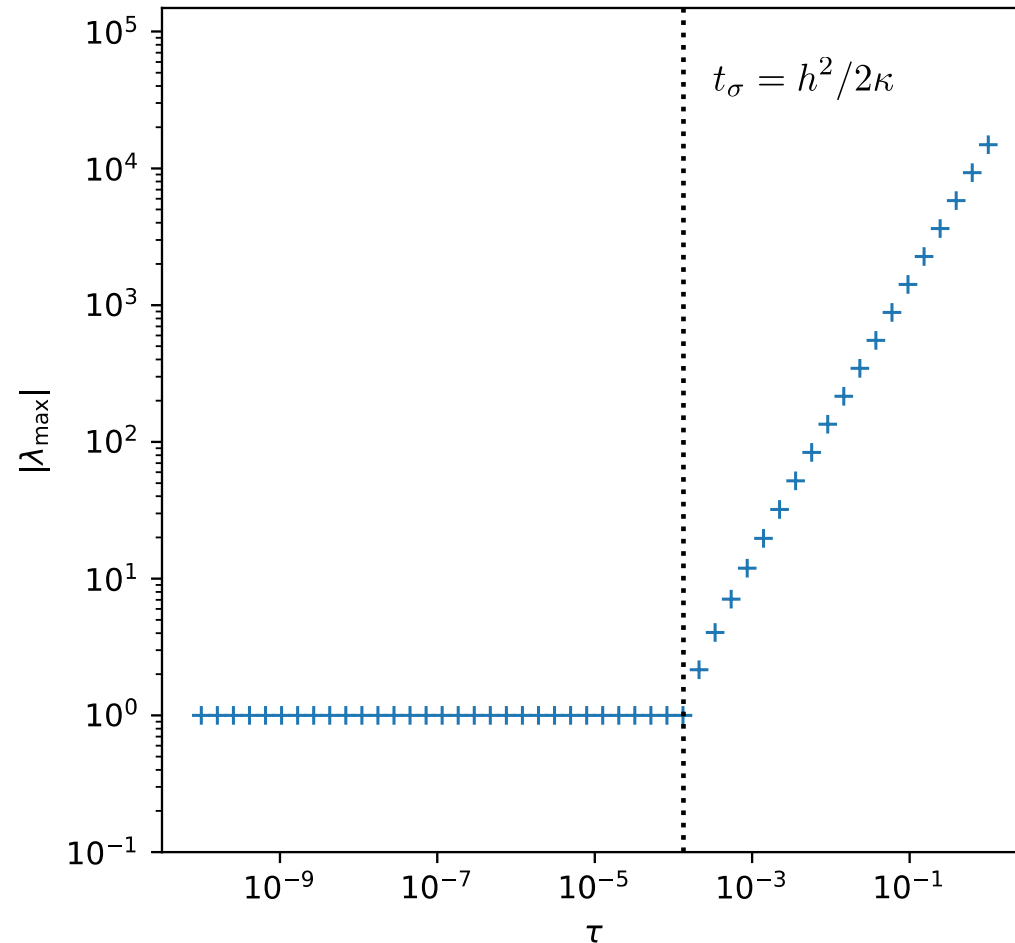
- We see that we will have divergence if we have any eigenvalues that are: $|\lambda_k| > 1$
- **Spectral radius of $\mathbf{A}$:** Magnitude of the largest eigenvalue

$$\rho(\mathbf{A}) = |\lambda_{\max}|$$

- Scheme is matrix stable if the spectral radius is less than or equal to unity

Stability of FTCS for diffusion equation with timestep

- 61 spatial grid points with unit length, $\kappa = 1$:



Some comments on stability analysis

- The two stability analyses discussed here are only suitable for linear PDEs
- Can use for nonlinear PDEs by linearizing around a reference state
- Often can use physical intuition to estimate stability criteria, as we did originally for CFL condition
- Note that we have not tested numerical schemes for unwanted dissipation (e.g., in the Lax method) or changes to dispersion
 - Can be studied with extensions of von Neumann analysis

Today's lecture: PDEs

- Stability analysis of PDEs
- Implicit schemes

Example for implicit schemes: Schrödinger equation

$$i\hbar \frac{\partial}{\partial t} \psi(x, t) = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} \psi(x, t) + V(x) \psi(x, t)$$

- Or:

$$i\hbar \frac{\partial \psi}{\partial t} = \mathcal{H} \psi$$

- Formal solution:

$$\psi(x, t) = \exp \left[-\frac{i}{\hbar} \mathcal{H} t \right] \psi(x, 0)$$

Discretizing the Schrödinger equation

- FTCS for the Schrödinger equation:

$$i\hbar \frac{\psi_j^{n+1} - \psi_j^n}{\tau} = -\frac{\hbar^2}{2m} \frac{\psi_{j+1}^n + \psi_{j-1}^n - 2\psi_j^n}{h^2} + V_j \psi_j^n$$

- Since the Hamiltonian is a linear operator:

$$i\hbar \frac{\psi_j^{n+1} - \psi_j^n}{\tau} = \sum_{k=0}^{N-1} H_{jk} \psi_k^n$$

- Where:

$$H_{jk} = -\frac{\hbar^2}{2m} \frac{\delta_{j+1,k} + \delta_{j-1,k} - 2\delta_{jk}}{h^2} + V_j \delta_{jk}$$

FTCS steps for Schrödinger equation

- Final FTCS scheme in matrix notation:

$$\Psi^{n+1} = \left(\mathbf{I} - \frac{i\tau}{\hbar} \mathbf{H} \right) \Psi^n$$

- First term in Taylor expansion of the formal solution for one time step:

$$\psi(x, t) = \exp \left[-\frac{i}{\hbar} \mathcal{H} t \right] \psi(x, 0)$$

Implicit schemes for the Schrödinger equation

- We have seen that the FTCS is numerically unstable for time steps that are too large
- Alternative approach: Apply the Hamiltonian to the future value of ψ

$$i\hbar \frac{\psi_j^{n+1} - \psi_j^n}{\tau} = \sum_{k=0}^{N-1} H_{jk} \psi_k^{n+1}$$

- Or:
$$\Psi^{n+1} = \Psi^n - \frac{i\tau}{\hbar} \mathbf{H} \Psi^{n+1}$$

- Solving for Ψ^{n+1} :

$$\Psi^{n+1} = \left(\mathbf{I} + \frac{i\tau}{\hbar} \mathbf{H} \right)^{-1} \Psi^n$$

Implicit FTCS scheme

- Implicit FTCS:

$$\Psi^{n+1} = \left(\mathbf{I} + \frac{i\tau}{\hbar} \mathbf{H} \right)^{-1} \Psi^n$$

- Compare with explicit FTCS:

$$\Psi^{n+1} = \left(\mathbf{I} - \frac{i\tau}{\hbar} \mathbf{H} \right) \Psi^n$$

- Equivalent as τ goes to 0 since for small ϵ :

$$\frac{1}{1 + \epsilon} \rightarrow (1 - \epsilon)$$

- Con: Implicit method requires evaluation of matrix inverse, which can be costly
- Pro: Unconditionally stable!

More accurate approximations: Crank-Nicholson

- As we saw before, numerically stable does not mean accurate
- More accurate scheme: **Crank-Nicholson**
 - Average of implicit and explicit FTCS:

$$i\hbar \frac{\psi_j^{n+1} - \psi_j^n}{\tau} = \frac{1}{2} \sum_{k=0}^{N-1} H_{jk} (\psi_k^n + \psi_k^{n+1})$$

- In matrix form:

$$\Psi^{n+1} = \Psi^n - \frac{i\tau}{2\hbar} \mathbf{H} (\Psi^n + \Psi^{n+1})$$

- Isolating the $n+1$ term:

$$\Psi^{n+1} = \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right)^{-1} \left(\mathbf{I} - \frac{i\tau}{2\hbar} \mathbf{H} \right) \Psi^n$$

Properties of Crank-Nicolson

$$\Psi^{n+1} = \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right)^{-1} \left(\mathbf{I} - \frac{i\tau}{2\hbar} \mathbf{H} \right) \Psi^n$$

- Unconditionally stable
- Centered in both space and time
- “Páde” approximation for exponential is
 - See (<https://en.wikipedia.org/wiki/Pade%28approximant%29>)

$$e^{-z} \simeq \frac{1 - z/2}{1 + z/2}$$

- CN can be interpreted as Páde for the formal solution
- Preserves the unitarity of e^{-z}

Example: Numerical solution of the Schrödinger equation

- Initial conditions: Gaussian wave packet
 - Localized around x_0
 - Width of σ_0
 - Average momentum of: $p_0 = \hbar k_0$

$$\psi(x, t = 0) = \frac{1}{\sqrt{\sigma_0} \sqrt{\pi}} \exp(i k_0 x) \exp \left[-\frac{(x - x_0)^2}{2\sigma_0^2} \right]$$

- Which is normalized so that:

$$\int_{-\infty}^{\infty} |\psi|^2 dx = 1$$

- Also, has the special property that uncertainty produce $\Delta x \Delta p$ is minimized ($\hbar/2$)

Propagation of wave packet in free space

- Wavefunction evolves like:

$$x \rightarrow x - \frac{p_0 t}{2m}, \quad \sigma_0^2 \rightarrow \alpha^2 \equiv \sigma_0^2 + \frac{i\hbar t}{m}$$

- So we have:

$$\psi(x, t) = \frac{1}{\sqrt{\sigma_0} \sqrt{\pi}} \frac{\sigma_0}{\alpha} \exp \left[ik_0 \left(x - \frac{p_0 t}{2m} \right) \right] \exp \left[-\frac{\left(x - x_0 - \frac{p_0 t}{2m} \right)^2}{2\alpha^2} \right]$$

- And for the probability density:

Remains a Gaussian in
time


$$P(x, t) = |\psi(x, t)|^2 = \frac{\sigma_0}{|\alpha|^2 \sqrt{\pi}} \exp \left[-\left(\frac{\sigma_0}{|\alpha|} \right)^2 \frac{\left(x - x_0 - \frac{p_0 t}{2m} \right)^2}{\sigma_0^2} \right]$$

Propagation of wave packet in free space

- By symmetry, max of Gaussian equals its expectation value:

$$\langle x \rangle = \int_{-\infty}^{\infty} x P(x, t) dx$$

- In time, it moves as: $\langle x \rangle = x_0 + \frac{p_0 t}{m}$

- And the wave packet spreads as:

$$\sigma(t) = \sigma_0 \sqrt{1 + \frac{\hbar^2 t^2}{m^2 \sigma_0^4}}$$

DEMO

- CN_schro.ipynb
- Start with $N=30$, $t=1$, $r=3$
 - Looks ok, but only move halfway
- Change $t=0.1$, $r=30$
 - Still only moves halfway
- Change $t=1$, $N=80$, $r=3$
 - Much better!
- Change $N=150$

DEMO

- Interactive plot for probability density

Why does the rough spatial discretization give errors?

- The reason is a poor representation of the initial conditions
- Rough discretization suppresses the higher wave number modes
 - Difficult to represent those modes on a coarse grid
- Because of this suppression, the discretized version has a lower momentum than $\psi(x,t)$

Can we avoid the taking the inverse of the matrix?

- As usual, we can trade taking the matrix inverse for solving a linear system of equations:

$$\begin{aligned}\Psi^{n+1} &= \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right)^{-1} \left(\mathbf{I} - \frac{i\tau}{2\hbar} \mathbf{H} \right) \Psi^n \\ &= \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right)^{-1} \left[2\mathbf{I} - \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right) \right] \Psi^n \\ &= \left[2 \left(\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right)^{-1} - \mathbf{I} \right] \Psi^n\end{aligned}$$

- Or:

$$\Psi^{n+1} = \mathbf{Q}^{-1} \Psi^n - \Psi^n, \quad \mathbf{Q} = \frac{1}{2} \left[\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right]$$

Crank-Nicolson for tridiagonal matrices

$$\Psi^{n+1} = \mathbf{Q}^{-1} \Psi^n - \Psi^n, \quad \mathbf{Q} = \frac{1}{2} \left[\mathbf{I} + \frac{i\tau}{2\hbar} \mathbf{H} \right]$$

- Now we can solve for the next timestep by solving the linear system:

$$\mathbf{Q}\chi = \Psi^n$$

- And then:

$$\Psi^{n+1} = \chi - \Psi^n$$

- Recall that for banded matrices, solving linear systems via, e.g., Gaussian elimination, is particularly efficient

DEMO

- CN_schro_no_inv.ipynb

Some comments in implicit schemes

- Recall that the killer app of implicit methods was that they are unconditionally stable
- Major downside is that for higher-dimensional problems, matrices become very large and difficult to manipulate
 - Can use approaches to separately perform implicit steps in different dimensions

After class tasks

- Homework 4 is posted, due Nov. 5, 2025
- Readings
 - Garcia Chapters 8 and 9
 - [Mike Zingale's notes on computational hydrodynamics](#)